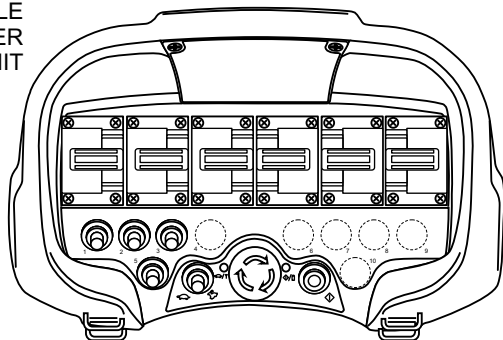


PORTABLE
CONTROLLER
UNIT
Type 48669

1A 2A 3A 4A 5A 6A
↕ ↕ ↕ ↕ ↕ ↕
1B 2B 3B 4B 5B 6B

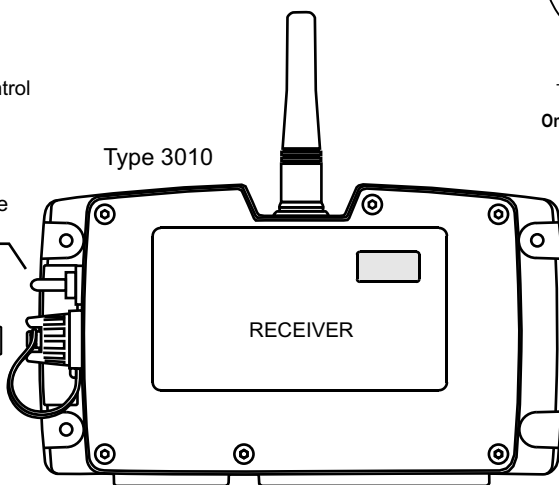


Cable used to
bypass radio mode
or to program
the radio remote control

L = 10 m

Manual/Off/Remote
switch selector

Type 3010



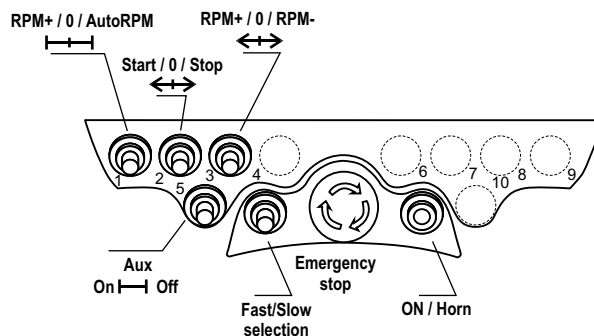
SWITCH MAP

left/up center right/down
SW1: 1 - 0 - 8
SW2: 2 > 0 < 3
SW3: 4 > 0 < 5
SW5: 6+9 - 0

⏹ - = detent
↔ >/< = spring return

OUTPUT MAP

pos	DF	OUT	pos	DF	OUT
1	1	1	11	10	12
2	3	2	12	11	13
3	4	3	13	12	14
4	7	4	14	13	-
5	31	5	15	9	-
6	5	6	16	8	-
7	32	-	17	37	-
8	2	9	18	34	-
9	6	10	19	35	-
10	33	11	20	36	-
Clacson/Horn			17	7	
Emergency Stop			40	8	

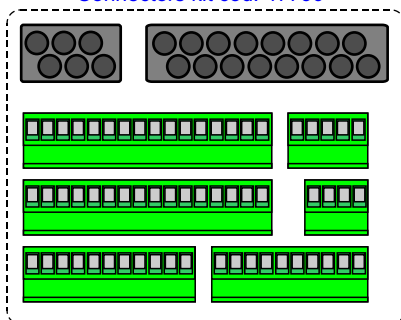


AutoRPM working switch description

When SW1 is on +RPM (left position)
Output Out1 remains always ON.

When SW1 is on AutoRPM (right position)
Output Out9 is ON while output Out1
turns ON only when a proportional lever is not in
center. Out1 turns OFF with a 6 seconds delay
after all levers have returned in center.

Connectors kit cod. 47790



- DV delay = 0.5 s
- The "Emergency stop" output (Out8) is active (positive) only when the PCU is on.

SW da scaricare: vedi tabella a parte

B=Crane
C=WMB
U= only SET1
1=12V
2=24V

FABERCOM		CODICE:	PR5MxHy6SS
DESC: Scanreco RC400 G2B radio remote control global view for HAWC with mini PCU			
FILE: ..\Scanreco\G2B\Produzione\PWM\Mini\PR5MxHy6SS_ie.cdr			
DATA: 01/09/14	FOGLIO 1	DI 2	

conn. K7	Signal	Description
K7.1	+Vdc	Power supply 12/24V
K7.2	GND	GND
K7.3	DV+	+ Dump Valve
K7.4	DV GND	GND

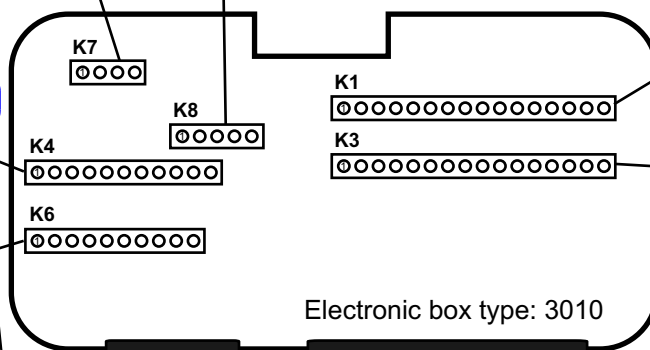
Power supply

DV output

conn. K4	Signal	Description
K4.1	out1	RPM+/AutoRPM
K4.2	out2	Start
K4.3	out3	Stop
K4.4	out4	RPM+
K4.5	out5	RPM-
K4.6	out6	- not used -
K4.7	GND	GND
K4.8	din1	- not used -
K4.9	din2	- not used -
K4.10	din3	SET2 selection
K4.11	+Vdc out	Positive in Remote

conn. K6	Signal	Description
K6.1	out7	Clacson
K6.2	out8	Emergency stop
K6.3	out9	AutoRPM selected
K6.4	out10	Aux
K6.5	GND	GND
K6.6	out11	- not used -
K6.7	out12	- not used -
K6.8	out13/din4	- not used -
K6.9	out14/ser.	- not used -
K6.10	GND	GND

Connector K8	Description
K8.1	CAN-H
K8.2	CAN-L
K8.3	GND
K8.4	CAN-H
K8.5	CAN-L



Electronic box type: 3010

For versions x="B" and x="C":
connect together when SET2 (slow speed) is not used.

Disconnecting **din3** from positive,
SET2 (slow speed, single movement allowed) is selected.

	Connector K1	Description
Function no. 1	K1.1	PWM 1a
	K1.2	GND
	K1.3	PWM 1b
	K1.4	-
Function no. 2	K1.5	PWM 2a
	K1.6	GND
	K1.7	PWM 2b
Function no. 3	K1.8	-
	K1.9	PWM 3a
	K1.10	GND
	K1.11	PWM 3b
Function no. 4	K1.12	-
	K1.13	PWM 4a
	K1.14	GND
	K1.15	PWM 4b
	K1.16	-

	Connector K3	Description
Function no. 5	K3.1	PWM 5a
	K3.2	GND
	K3.3	PWM 5b
	K3.4	-
Function no. 6	K3.5	PWM 6a
	K3.6	GND
	K3.7	PWM 6b
Function no. 7	K3.8	-
	K3.9	PWM 7a
	K3.10	GND
Function no. 8	K3.11	PWM 7b
	K3.12	-
	K3.13	PWM 8a
	K3.14	GND
	K3.15	PWM 8b
	K3.16	-

Hawe proportional outputs

FABERCOM	CODICE: PR5MxHy6SS
DESC: Scanreco RC400 G2B radio remote control for Hawe. Connections inside the central unit.	
FILE: ..\Scanreco\G2B\Produzione\PWM\Mini\PR5MxHy6SS_ie.cdr	
DATA: 01/09/14	FOGLIO 2 DI 2